

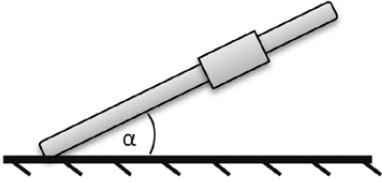
Project Planning Sheet

Ballscrew

HIWIN®

Motion Control & Systems

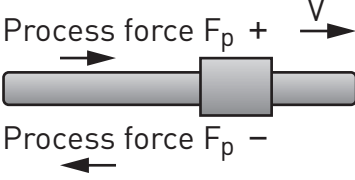
Customer data	
Company:	Contact person:
Project:	

Mounting position  $\alpha = 0^\circ$ horizontal <input type="checkbox"/> $\alpha = 90^\circ$ vertical <input type="checkbox"/> $\alpha = ___\circ$	System parameters Nut type: Tolerance class: T5 <input type="checkbox"/> T7 <input type="checkbox"/> Other <input type="checkbox"/> _____ Ballscrew diameter d_s [mm] Lead P [mm] Total length l_g [mm] Load m [kg] Thread length l_s [mm] Friction force F_R [N] Standard (axial play) <input type="checkbox"/> free of play <input type="checkbox"/> preload <input type="checkbox"/> _____ % Other information:
--	---

Type of bearing Fixed - Fixed <input type="checkbox"/> Fixed - Supported <input type="checkbox"/> Supported - Supported <input type="checkbox"/> Fixed - Free <input type="checkbox"/>	Lubrication Oil <input type="checkbox"/> Grease <input type="checkbox"/>	Operating temperature min. _____ °C max. _____ °C Special operating conditions (e.g. dust, fluids, vibrations)
---	---	--

Cycle data						
Phase n	Direction of motion, see (1)	Process force (\pm) F_p [N], see (2)	Acceleration/deceleration a [m/s ²]	Rotation speed [1/min]		Time slice* [%]
				n ₁	n ₂	
1						
2						
3						
4						
5						
6						
7						
8						
9						

* without downtime periods

Way of the motion sequence described above	$l_{zyk.} =$ [mm]	Account the sign (2)  Process force $F_p +$ Process force $F_p -$
Total travel time	$t_{zyk.} =$ [s]	
Max. velocity	$v_{max} =$ [m/s]	
Other information:		(1) Direction of motion: left, right, up, down

Operation time Cycles/hour [z/h] = Working days/year [d/y] =	1-shift-operating <input type="checkbox"/> 2-shift-operating <input type="checkbox"/> 3-shift-operating <input type="checkbox"/>	Required lifetime Cycles [z] $L_z =$ Kilometers [km] $L_{km} =$ Years [y] $L_y =$
---	--	---

Other notes
