

# Project Planning Sheet

## Servo drive with servo motor


# HIWIN®

Motion Control & Systems

Company:	Processed by:
Technical consultant:	Date:
Purchasing consultant:	Project name:

**Project plan** (current state of project/schedule/quantity/aimed price)

**Application** (industry sector, machine type, usage etc.)

Existing project	
	<b>Servo motor</b> Manufacturer: Type <sup>1)</sup> : Power:            50W <input type="checkbox"/> 100W <input type="checkbox"/> 200W <input type="checkbox"/> 400W <input type="checkbox"/> 750W <input type="checkbox"/> 1000W <input type="checkbox"/> Motor brake:        yes <input type="checkbox"/> no <input type="checkbox"/> Encoder interface:
	<b>Servo drive</b> Manufacturer: Type <sup>2)</sup> : Supply voltage: 230V, 1-phase <input type="checkbox"/> 400V, 3-phase <input type="checkbox"/> Power:            400W <input type="checkbox"/> 1000W <input type="checkbox"/> Interface: EtherCAT CoE <input type="checkbox"/> EtherCAT mega-ulink <input type="checkbox"/> PROFINET <input type="checkbox"/> Pulse-direction/±10V <input type="checkbox"/> Other:
	Cables            Motor/encoder        3m <input type="checkbox"/> 5m <input type="checkbox"/> 7m <input type="checkbox"/> 10m <input type="checkbox"/>
	Line filter        yes <input type="checkbox"/> no <input type="checkbox"/>

<sup>1)</sup> Order code of the manufacturer: e.g. EM1-C-M-20-2-0-E-0-A

[Add manufacturer data sheet]

<sup>2)</sup> Order code of the manufacturer: e.g. ED1F-EN-0422-01

[Add manufacturer data sheet]

# Project Planning Sheet

## Servo drive with servo motor



Motion Control & Systems

New project	
Inertia (without motor) in $\text{kgm}^2$ :	<p>The graph shows a trapezoidal speed profile. The vertical axis is labeled 'n' and the horizontal axis is labeled 'Operating cycle'. The profile consists of four phases: <math>t_a</math> (acceleration), <math>t_c</math> (constant speed), <math>t_d</math> (deceleration), and <math>t_p</math> (stop). Vertical dashed lines mark the boundaries between these phases.</p>
n in rev./min:	
Acceleration in $\text{rad/s}^2$ :	
$t_a$ in s:	
$t_c$ in s:	
$t_d$ in s:	
$t_p$ in s:	
Additional torque in Nm:	
Options	Interface servo drive
Motor brake <input type="checkbox"/>	EtherCAT CoE <input type="checkbox"/>
Encoder absolute singleturn <input type="checkbox"/>	EtherCAT mega-ulink <input type="checkbox"/>
Encoder absolute multiturn <input type="checkbox"/>	PROFINET <input type="checkbox"/>
Line filter <input type="checkbox"/>	Pulse-direction/ $\pm 10V$ <input type="checkbox"/>
	Other: <input type="checkbox"/>
Supply voltage	
230V, 1-phase <input type="checkbox"/>	400V, 3-phase <input type="checkbox"/>
Cables motor/encoder	
3m <input type="checkbox"/>	5m <input type="checkbox"/>
7m <input type="checkbox"/>	10m <input type="checkbox"/>

**Notes:**